

Huygens Subgridding for Frequency-Dependent Finite-Difference Time-Domain Method

Maksims Abalenkovs¹ Fumie Costen¹ Jean-Pierre Bérenger²

¹School of Electrical and Electronic Engineering
The University of Manchester

²Centre d'Analyse de Défense
Arcueil, France

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Outline

- 1 Motivation
- 2 Finite-Difference Time-Domain (FDTD) Method
- 3 Huygens Subgridding (HSG)
- 4 Simulation Results
- 5 Instability in HSG

Motivation

- Character of electromagnetic wave propagation
- Modern engineering projects:
 - ▶ very large problem size
 - ▶ fine geometric details
 - ▶ dielectric material properties.
- Answer: efficient large-scale Maxwell's equations solver

Finite-Difference Time-Domain Method

Regular FDTD [1]:

$$\frac{\partial \mathbf{H}}{\partial t} = -\frac{1}{\mu} \nabla \times \mathbf{E}, \quad \frac{\partial \mathbf{D}}{\partial t} = \nabla \times \mathbf{H}$$

Debye relaxation:

$$\mathbf{D} = \varepsilon_0 \varepsilon_r \mathbf{E} = \varepsilon_0 \left(\varepsilon_\infty + \frac{\varepsilon_s - \varepsilon_\infty}{1 + j\omega\tau_1} + \frac{\sigma}{j\omega\varepsilon_0} \right) \mathbf{E}$$

Courant-Friedrichs-Lewy stability [2]:

$$S \equiv \Delta t c \sqrt{\frac{1}{\Delta x^2} + \frac{1}{\Delta y^2} + \frac{1}{\Delta z^2}}, \quad S \leq 1$$

DEH Approach

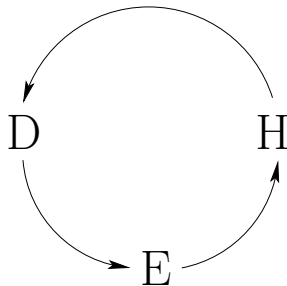
calc $H_*^{n-\frac{1}{2}}$

calc D_*^n

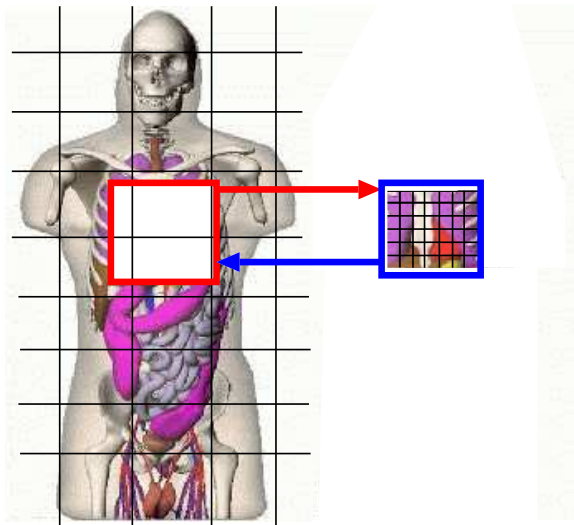
calc D_{src}^n

calc E_*^n

calc E_{ABC}^n



Subgridding Example



General Subgridding

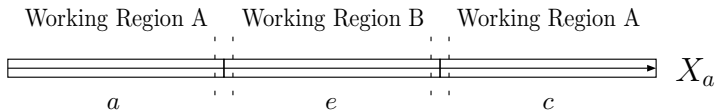
- FDTD efficiency improvement \longrightarrow *Subgridding*
- Idea: simulation space = $n \times$ subspaces with different Δt and Δs
- Key issues:
 - ▶ compromise: efficiency \longleftrightarrow accuracy
 - ▶ subgridding interface: stability and accuracy
 - ▶ parallelisation
 - ▶ number of grid refinement levels
 - ▶ subgridding ratio $r = \frac{\Delta s_a}{\Delta s_b}$, ($r_{sim} \leq 7$)
 - ▶ temporal increments:
 - synchro unistep $\longrightarrow \Delta t_a = \Delta t_b$
 - synchro multistep $\longrightarrow \Delta t_a = r \cdot \Delta t_b$.

Huygens Subgridding

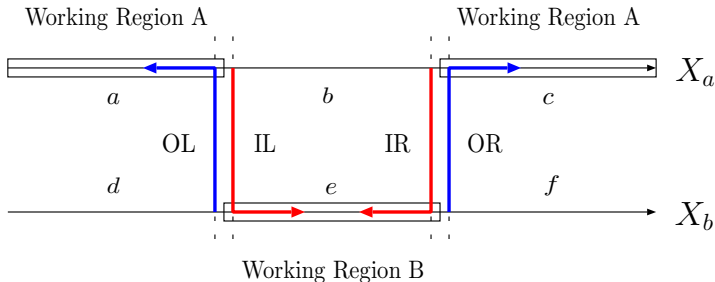
- Interface: Huygens Surfaces (HS), little reflection
- Influence: equivalent currents
- Time step: synchro multistep $\rightarrow \Delta t_a = r \cdot \Delta t_b$
- Subgridding ratio: $r = \frac{\Delta s_a}{\Delta s_b} = \frac{\Delta t_a}{\Delta t_b}$, ($r_{sim} \leq 50$).

HSG Inner and Outer Surfaces

Single space:



Decomposition: non-working regions \rightarrow no influence



HSG Decomposition into Subspaces

Original Problem

Equivalent Problem

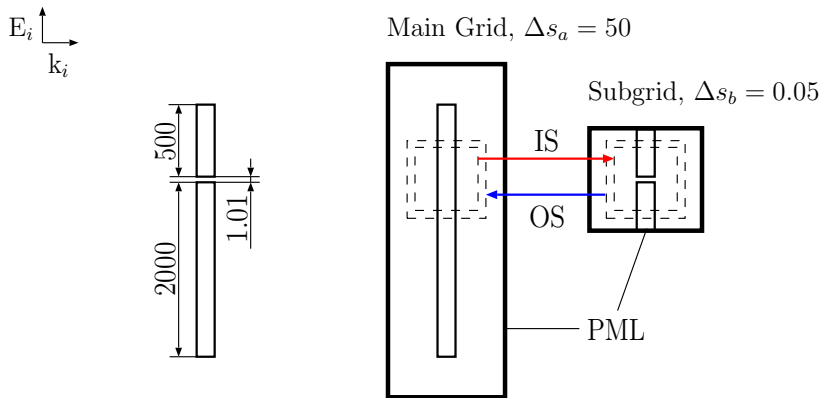


Figure: Thin Slot, 2D, $r = 99$ [3]

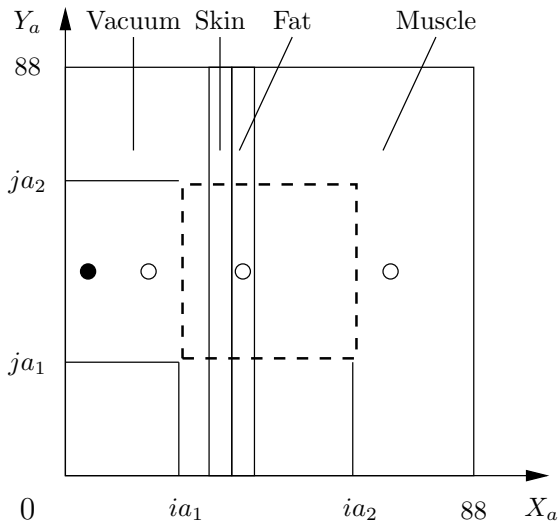
Input Parameters

| Parameter | HSG | DEH (b) |
|-------------|---------|---------|
| n_x | 88 | 264 |
| t_{max} | 1000 | 3000 |
| r | 3 | — |
| aISIS | 26 | — |
| source type | soft | soft |
| f_w | 3.1 GHz | 3.1 GHz |
| S | 0.93 | 0.93 |
| T_x | 19 | 57 |

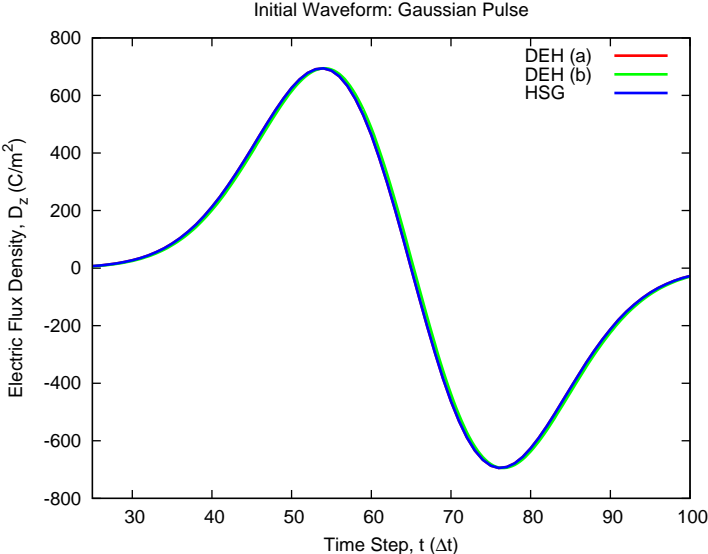
Debye Media Parameters

| Medium | $\sigma, \left[\frac{S}{m} \right]$ | $\epsilon_S,$ | $\epsilon_\infty,$ | $\tau_1, [s]$ |
|--------|--------------------------------------|---------------|--------------------|-------------------------|
| vacuum | 0 | 1 | 1 | 0 |
| fat | 0.03434 | 6.12803 | 3.7310 | $1.7996 \cdot 10^{-11}$ |
| skin | 0.41326 | 76.5550 | 19.534 | $1.6742 \cdot 10^{-11}$ |
| muscle | 0.69874 | 67.2970 | 21.015 | $1.3560 \cdot 10^{-11}$ |

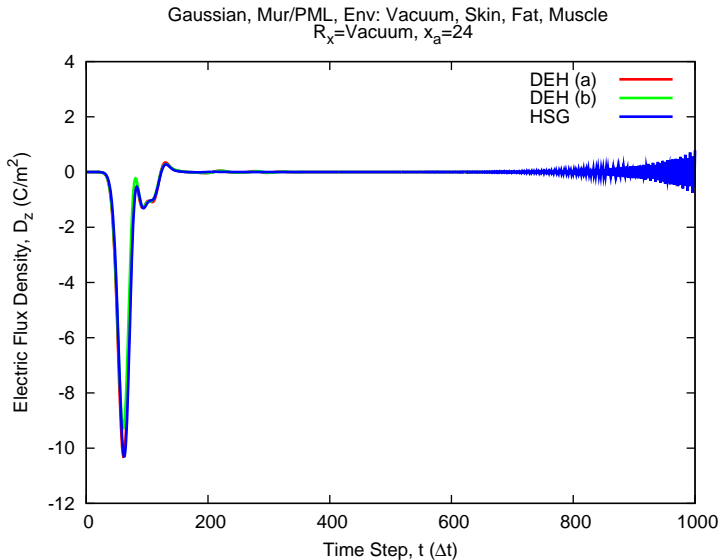
Scenario Setting, 2D



Initial Waveform: Gaussian Pulse

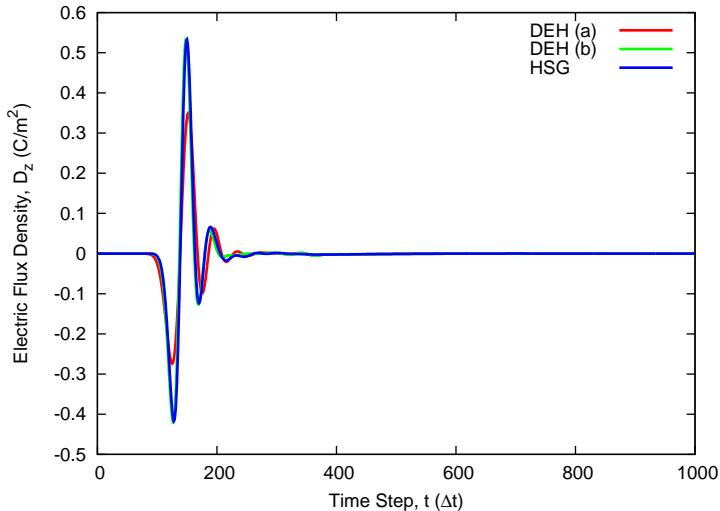


$$R_x = \text{Vacuum}, x_a = 24$$



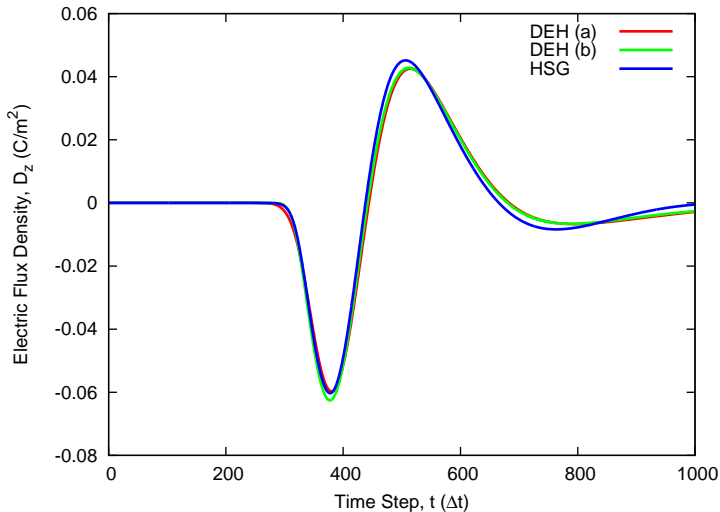
$$R_x = \text{Fat}, x_a = 41$$

Gaussian, Mur/PML, Env: Vacuum, Skin, Fat, Muscle
 $R_x = \text{Fat}, x_a = 41$



$$R_x = \text{Muscle}, x_a = 64$$

Gaussian, Mur/PML, Env: Vacuum, Skin, Fat, Muscle
 $R_x = \text{Muscle}, x_a = 64$



Instability in HSG

Dispersion relation:

$$\sin\left(\frac{\omega\Delta t}{2}\right) = \frac{c\Delta t}{\Delta x} \sin\left(\frac{k_x\Delta x}{2}\right).$$

Wave frequency:

$$f_w = \begin{cases} \text{low,} & k_x \in \mathbb{R}, \text{ travelling waves,} \\ \text{high, } \sin\left(\frac{k_x\Delta x}{2}\right) > 1, & k_x \in \mathbb{C}, \text{ evanescent waves.} \end{cases}$$

Instability frequency [3]:

$$f_{inst} \approx f_{tran} = \frac{1}{\pi\Delta t} \arcsin\left(\frac{c\Delta t}{\Delta x}\right).$$

Filtering in HSG

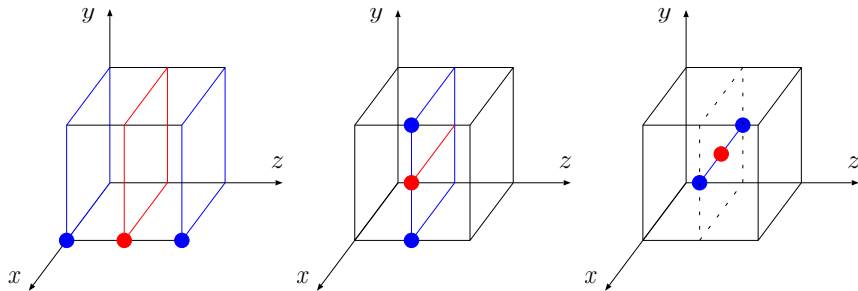
Filter equivalent currents IS:

$$\bar{E}_{a(IS)} = \frac{E_{a(IS-1)} + E_{a(IS)}}{2} = \frac{1}{2}E_{a(IS-1)} + \frac{1}{2}E_{a(IS)}.$$

Cosine filter:

$$F_1(k_x) = \frac{e^{jk_x \Delta x_a} + 1}{2} = e^{\frac{jk_x \Delta x_a}{2}} \cos\left(\frac{k_x \Delta x_a}{2}\right).$$

Filtering Implementation



Conclusion

- HSG successfully applied to FD–FDTD 3D:
 - ▶ efficient Maxwell's equations solver
 - ▶ dielectric material properties
 - ▶ late-time instable.

Future Work:

- apply method to human body model \longrightarrow defibrillation parameters
- experiment with different digital filters
- parallelise HSG–FD–FDTD 3D.

Bibliography I



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Jean-Pierre Bérenger

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Discussion:

- thank you for attention
- questions and answers.